system, in the limit of an infinite number of oscillators, could be described by three ordinary differential equations. However, Pikovsky and Rosenblum [20] showed, using the ansatz of Watanabe and Strogatz [21], that the Ott/Antonsen (OA) ansatz did not completely d



A, B, C and D), but where each member of the ensemble has a randomly chosen set of frequencies  $\{ \begin{array}{c} 1 \\ j \\ \end{pmatrix}$  and  $\{ \begin{array}{c} 2 \\ j \\ \end{pmatrix}$  (these both come from the same distribution g, and g is the same for each member of the ensemble). Letting the number of members of the ensemble go to infinity we describe the state of population 1 by the probability density function

$$f^{1}(1, 1, 2, \dots, N; 1, 2, \dots, N; t)$$

and population 2 by the function

$$f^{2}(\begin{array}{cccccccc} 2 & 2 & 2 & 2 & 2 & 2 & 2 \\ 1 & 2 & \cdots & N & 1 & 2 & \cdots & N; t \end{pmatrix}$$

which, by conservation of oscillators [4, 18], satisfy

$$\frac{\mathbf{f}}{\mathbf{t}} + \sum_{j=1}^{N} \frac{\mathbf{d}_{j}}{j} = 0$$
(7)

for

and

$$A_{j} = \frac{1}{N} \sum_{k=1}^{N} A_{jk} \overline{a}_{k} \qquad B_{j} = \frac{1}{N} \sum_{k=1}^{N} B_{jk} \overline{b}_{k} \qquad (27)$$

$$C_{j} = \frac{1}{N} \sum_{k=1}^{N} C_{jk} \overline{b}_{k} \qquad D_{j} = \frac{1}{N} \sum_{k=1}^{N} D_{jk} \overline{a}_{k} \qquad (28)$$

The interpretation of the  $a_k$  is that the magnitude of  $a_k$  gives the "peaked-ness" of the angular distribution over the ensemble of the  $\frac{1}{k}$ — the closer  $|a_k|$  is to 1 the more peaked the distribution, while  $|a_k| = 0$  corresponds to a uniform angular distribution. The argument of  $a_k$  gives the phase about which the distribution of the  $\frac{1}{k}$  are peaked. Similarly for the  $b_k$  and population 2.

Note that when A, B, C and D are full, there exists a solution of (23)-(28) for which  $a_k = a$  and  $b_k = b \forall k$ , where a and b are governed by the two complex equations studied by Laing [3]:

$$\frac{da}{dt} = -a + (e^{i}/2)(\mu a + b) - (e^{-i}/2)(\mu \overline{a} + \overline{b})a^{2}$$
(29)

$$\frac{db}{dt} = -b + (e^{i}/2)(\mu b + a) - (e^{-i}/2)(\mu \overline{b} + \overline{a})b^{2}$$
(30)

If = 0, (29)-(30) are the same equations as studied by Abrams et al. [7]. As Barlev et al. [8] noted, this type of sychronised solution, for which  $a_k = a$  and  $b_k = b \forall k$ , also exists when the coupling matrices all have the same row sum, i.e. all of the oscillators have the same in-degree. Note that (29)-(30) were derived by Abrams et al. [7] not by averaging over an infinite ensemble of finite networks as done by Barlev et al. [8], but by considering the limit  $N \rightarrow \infty$  for a single network with full connectivity.

## **III. RESULTS**

We now consider the solutions of (23)-(28). For concreteness we set = 0.001; we also define = /2 -







FIG. 7: The values of  $_{sn}$  for which there is a saddle-node bifurcation of fixed points of (25)-(28) and (31)-(32) for Erdös-Rényi-type random matrices A, B, C and D, as a function of p. At each value of p, 10 realisations of the random matrices were used, and the mean and standard deviation of the 10  $_{sn}$  are shown. Other parameters: N = 300, E = 0.2, = 0.001.



FIG. 8: Values of E at which a Hopf bifurcation of a stable stationary chimera state occurs for an Erdös-Rényi-type network, for different values of p. At each value of p, 10 realisations of the random matrices were used, and the mean and standard deviation of the 10 values of E are shown. Other parameters: N = 300, = 0.05, = 0.001.

## 2. Chung-Lu-type networks

We now consider a second type of perturbation from the fully-connected case in which edges are removed preferentially so as to create a specific skewed degree distribution. The algorithm we use to create these networks is motivated by the Chung-Lu algorithm [26]. We begin by assigning to each oscillator in a subnetwork a weight  $w_i = N(i/N)^r$ , where i = 1, 2, ... N is the oscillator number within the network.







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